4.31. **(a)** Show that the three LTI systems with impulse responses

$$h_1(t) = u(t),$$

$$h_2(t) = -2\delta(t) + 5e^{-2t}u(t),$$

and

$$h_3(t) = 2te^{-t}u(t)$$

all have the same response to $x(t) = \cos t$.

(b) Find the impulse response of another LTI system with the same response to $\cos t$.

This problem illustrates the fact that the response to $\cos t$ cannot be used to specify an LTI system uniquely.

4.32. Consider an LTI system S with impulse response

$$h(t) = \frac{\sin(4(t-1))}{\pi(t-1)}.$$

Determine the output of S for each of the following inputs:

(a) $x_1(t) = \cos(6t + \frac{\pi}{2})$

(b) $x_2(t) = \sum_{k=0}^{\infty}(\frac{1}{2})^k \sin(3kt)$

(c) $x_3(t) = \frac{\sin(4(t+1))}{\pi(t+1)}$

(d) $x_4(t) = (\frac{\sin 2t}{\pi t})^2$

4.33. The input and the output of a stable and causal LTI system are related by the differential equation

$$\frac{d^2y(t)}{dt^2} + 6\frac{dy(t)}{dt} + 8y(t) = 2x(t)$$

(a) Find the impulse response of this system.

(b) What is the response of this system if $x(t) = te^{-2t}u(t)$?

(c) Repeat part (a) for the stable and causal LTI system described by the equation

$$\frac{d^2y(t)}{dt^2} + \sqrt{2}\frac{dy(t)}{dt} + y(t) = 2\frac{d^2x(t)}{dt^2} - 2x(t)$$

4.34. A causal and stable LTI system S has the frequency response

$$H(j\omega) = \frac{j\omega + 4}{6 - \omega^2 + 5j\omega}.$$

(a) Determine a differential equation relating the input $x(t)$ and output $y(t)$ of S.
(b) Determine the impulse response $h(t)$ of S.
(c) What is the output of S when the input is

$$x(t) = e^{-4t}u(t) - te^{-4t}u(t)?$$

4.35. In this problem, we provide examples of the effects of nonlinear changes in phase.
(a) Consider the continuous-time LTI system with frequency response

$$H(j\omega) = \frac{a - j\omega}{a + j\omega},$$

where $a > 0$. What is the magnitude of $H(j\omega)$? What is $\sphericalangle H(j\omega)$? What is the impulse response of this system?
(b) Determine the output of the system of part (a) with $a = 1$ when the input is

$$\cos(t/\sqrt{3}) + \cos t + \cos \sqrt{3}t.$$

Roughly sketch both the input and the output.

4.36. Consider an LTI system whose response to the input

$$x(t) = [e^{-t} + e^{-3t}]u(t)$$

is

$$y(t) = [2e^{-t} - 2e^{-4t}]u(t).$$

(a) Find the frequency response of this system.
(b) Determine the system's impulse response.
(c) Find the differential equation relating the input and the output of this system.

ADVANCED PROBLEMS

4.37. Consider the signal $x(t)$ in Figure P4.37.
(a) Find the Fourier transform $X(j\omega)$ of $x(t)$.
(b) Sketch the signal

$$\tilde{x}(t) = x(t) * \sum_{k=-\infty}^{\infty} \delta(t - 4k).$$

(c) Find another signal $g(t)$ such that $g(t)$ is not the same as $x(t)$ and

$$\tilde{x}(t) = g(t) * \sum_{k=-\infty}^{\infty} \delta(t - 4k).$$